

PORT SUSPEND/RESUME ACTIONS
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void active_actions () {
    active = TRUE;
    initiate_resume = resume_target = FALSE;
}

void suspend_initiator_actions () {
    connect_timer = 0;
    suspend_initiator = FALSE;           // clear the suspend request
    wait((connect_timer >= NOTIFY_HOLD) || (!port_status));
    if (!port_status)                   //TpBias driven low by target
        TpGen = LOW;                    // drive TpBias
}

void suspend_target_actions () {
    suspend_target = FALSE;
    connect_timer = 0;                  // start the timer
    TpGen = LOW;                        // drive TpBias low to Initiator
    wait ((connect_timer >= BIAS_HOLD) || (!port_status));
                                        // wait for initiator to drive TpBias
}

void suspend_failed_actions () {       // legacy target
    if (chg_int_en && link_active)
        PH_EVENT.ind (INTERRUPT); // notify higher layers of fault
    else if (resume && !link_active) // or wake up the LINK
        PH_EVENT.ind (LINK_ON);
    port_power = FALSE;
}

void disconnected_actions () {
    port_power = TRUE;                 // Power up the port
    TpGen = HiZ;                       // But don't drive TpBias
    wait (port_functional);            // Clock is running
    active_en = FALSE;                 // prevents port from being active until bus reset
    connection_in_progress = FALSE;
    if (!debouncing) {                // Don't reset if debouncing a new connection
        if (child)                    // Parent still connected?
            isbr = TRUE;              // Yes, arbitrate for short reset
        else
            ibr = TRUE;               // No, core transits to R0.
    }
    if (connected || fault)
        if (link_active && chg_int_en)
            PH_EVENT.ind (INTERRUPT); // notify higher layers of disconnect or !fault
        else if (!link_active && resume) // wake up the link
            PH_EVENT.ind (LINK_ON);
    connected = FALSE;                // Clear STATUS_A.con
    fault = FALSE;                    // Clear CONTROL_SET.fault
    debouncing = FALSE;
    initiate_resume = resume_target = FALSE;
    port_power = FALSE;                // Shutdown the port.
}
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void suspended_actions () {
    port_power = TRUE;           // Power up the port
    wait (port_functional);      // Clock is running
    if (link_active && chg_int_en)
        PH_EVENT.ind (INTERRUPT); // notify higher layers of !disable or !fault or suspend
    else if (!link_active && resume) // wake up the link
        PH_EVENT.ind (LINK_ON);
    initiate_resume = resume target = FALSE;
    fault = FALSE;
    TpGen = LOW;                 // drive TpBias low and then release
    wait (con_status == TRUE);   // wait to eliminate false disconnect
    port_power = FALSE;         // turn off bias generator
}

void resume_actions () {
    port_power = TRUE;           // Power up the port
    wait (port_functional);      // Clock is running
    if (port_status)
        resume_target = resume_all = TRUE; // This port is a resume target and resume all suspended ports
    TpGen = HIGH;                // drive TpBias to resume target or resume initiator
    connect_timer = 0;           // start timer
    wait ((connect_timer >= DETECT_MIN) || (port_status == TRUE)); // wait for target to drive TpBias
    if (port_status) {
        fault = FALSE;
        if (chg_int_en && link_active)
            PH_EVENT.ind (INTERRUPT); // notify higher layers of port resuming
        else if (!link_active && resume) // or wake up the link
            PH_EVENT.ind (LINK_ON);
    }
}

void resume_failed_actions () {
    if (!fault) {
        fault = TRUE;
        if (chg_int_en && link_active)
            PH_EVENT.ind (INTERRUPT); // notify higher layers of fault
        else if (!link_active && resume)
            PH_EVENT.ind (LINK_ON); // or wake up the LINK
    }
    TpGen = LOW;                 // drive TpBias low and then release
    wait (con_status == TRUE);   // wait to eliminate false disconnect
    port_power = FALSE;         // return to suspend state
}

void disabled_actions () {
    port_power = TRUE;           // Power up the port
    wait (port_functional);      // Clock is running
    if (chg_int_en && link_request)
        PH_EVENT.ind (INTERRUPT); // notify higher layers of disable
    else if (!link_active && resume)
        PH_EVENT.ind (LINK_ON);
    port_power = FALSE;         // Stop driving TpBias
}

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void connect_debounce_actions () {
    port_power = TRUE;           // Power up the port
    TpGen = HiZ;                // But don't drive TpBias
    wait (port_functional);     // Clock is running
    connection_in_progress = TRUE;
    connect_timer = 0;          // Start the timer
    wait (!con_status || connected || connect_timer >= (isolated_node()) ? 2 * CONNECT_TIMEOUT: CONNECT_TIMEOUT);
    // Debounce con_status
    // connected == TRUE when reset_detected() == TRUE
    if (con_status) {          // Still connected?
        connected = TRUE;     // Yes, set STATUS_A.con
        if (isolated_node()) // Can we arbitrate?
            ibr = TRUE;      // No, core transits to R0.
        else
            isbr = TRUE;     // Yes, arbitrate for short reset.
    }
    connection_in_progress = FALSE;
}

```