S/R Actions and State Diagram

- Documents and Objectives
- Partitioning of Work between Node and Port
- Definition of Port States
- Definition of Node States

New States

Changes to Existing C Code

- Suspend Transaction/Propagation
- Resume
- Port Transitions

Documents and Objectives

- Documents
 - 97-031r8 Suspend/Resume Proposal
 - 97-053r0 Port S/R Actions (C code)
 - 97-054r0 Node S/R Actions (C code)
 - 97-055r0 Port S/R State Diagram
- Objectives of Actions and State Diagram
 Detailed Review of S/R Proposal
 Normative part of S/R

Partitioning of Work

Node

PHY register access packets Arbitration signals (Suspend, Disable) Coordinator for multi-port actions

Port

Drives TpBias (HIGH, LOW and HiZ) Receives TpBias Handshakes with peer port

Definition of Port States

- Disconnected* = !connected & !port_status
- Suspended* = connected & !port_status
- Connected (active) = connected & port_status
- Register Bits
 Status_A.con = connected
 Status_A.bias = port_status
 - Control_Set.suspend = !port_status

* Port is suspended and consumes less than 1.65 milliwatts

Definition of Port States (cont'd)

- Disabled*
 Control_Set.disable
- Resume
 Transition from power-down to active
- Suspend Initiator/Target
 Transition from active to power-down
- Failed Resume*/Suspend*
 Peer port failed to handshake
 Control_Set.fault

Definition of Node States

- Port Register Transmit
 Response to PHY register access packet.

 Similar to Self-ID Transmit.
- Node Suspend Target
 Entered by receiving RX_SUSPEND.

 Suspends all active ports.
- Port Change (free running)
 Notifies node controller of any change in port registers.
 Triggers resume_event.

Definition of Node States (cont'd)

- Node Resume (free-running)
 Detects sleep changing from TRUE to FALSE.
 Resumes all suspended ports.
- Node Suspend (not in rev 0.41)
 Sets sleep if LPS is FALSE and all ports powered-down.
- Resume Event (entered when resume_event = TRUE)
 Resumes the node based on its resume status:
 BOUNDARY INITIATOR, BOUNDARY TARGET,
 RESUME INITIATOR, RESUME TARGET.

Changes to Existing C Code

- connection_status
 Only updates "connected" while power_down is TRUE.
 Monitors con_status instead of port_status.
- reset_start_actions
 Transmits TX_SUSPEND, TX_DISABLE.
- receive_actions/transmit_actions
 Detects PHY register access packets.

Suspend Transaction

Suspend Initiator

Receives PHY access packet (receive)

- Transmits PHY response packet (port register transmit)
- Transmits BUS_RESET andTX_SUSPEND (reset start)
- Waits for port_status to go LOW(suspend initiator)
- Drives TpBias LOW (suspended)

Suspend Target

- Receives PHY access packet
- Transmits PHY response packet Receives PHY response packet
 - Receives and repeats
 TX_SUSPEND (receive)
 - Drives TpBias LOW (suspend target)
 - Waits for port_status to go LOW (suspend target)
 - (suspended)

port actions node actions

Suspend Propagation

Suspend Target/Initiator

Suspend Target

- Receives PHY access packet
- Receives PHY access packet
- Receives PHY response packet Receives PHY response packet
- Receives and repeats TX_SUSPEND (receive)

- Receives and repeats TX_SUSPEND (receive)
- Waits for port_status to go LOW(suspend initiator)
- Drives TpBias LOW (suspend target)

Drives TpBias LOW (suspended)

- Waits for port_status to go LOW (suspend target)
- (suspended)

node actions

Resume

node actions

Resume Initiator

- LPS goes active
- Resume all suspended ports(node resume)
- Drives TpBias HIGH and waits for port_status equals TRUE (resume)
- Waits for port_status going TRUE (resume-active)
- Wait 5*RESET_DETECT
 If BUS_RESET detected, then attempt short reset.
 (resume event)

Boundary Target

- At least one port active and one port suspended
- Suspended port detects port_status going TRUE (suspended - resume)
- Drives TpBias HIGH (resume-active)
- Detects change in port_status (port change)
- Wait 2*RESET_DETECT and issue short reset.

node actions

port actions